

## How efficiently can we

- find the root of a tree,
- solve the prefix problem, if elements are given not by an array, but by a linked list?
  - For instance, which time is sufficient to determine a maximal element in a linked list?
- parallelize the traversal of a possibly deep tree?
- evaluate arithmetic expressions?

We encounter important algorithmic methods:

- the doubling technique (pointer jumping),
- Euler tours
- and tree contraction.

# Pointer Jumping

A forest  $F$  is represented by

- its set of nodes  $V = \{1, \dots, n\}$
- and by an array “parent”:  $\text{parent}[i]$  is the parent of node  $i$ .  
(If  $i$  is a root, then  $\text{parent}[i] = i$ .)

Determine the respective root for all nodes in parallel.

Finding the root via pointer jumping:

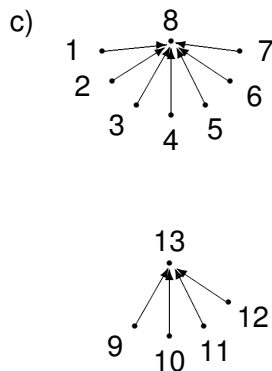
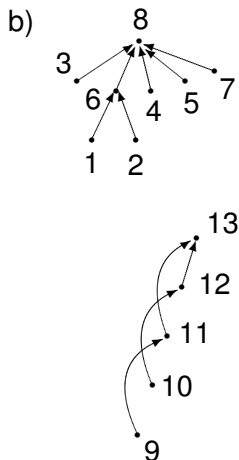
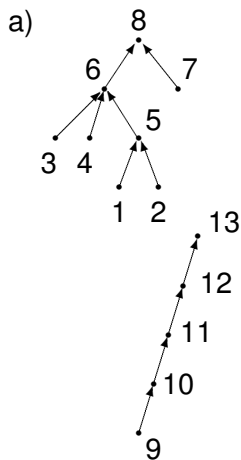
for  $i = 1$  to  $n$  pardo

while  $\text{parent}[i] \neq \text{parent}[\text{parent}[i]]$  do  
//  $\text{parent}[i]$  is different from the root.

$\text{parent}[i] = \text{parent}[\text{parent}[i]]$ ;   // We climb upwards.

Output  $(i, \text{parent}[i])$ ;

# Pointer Jumping: Examples



# Pointer Jumping: The Analysis

- Pointer jumping is a CREW algorithm, since the parent array is concurrently read, but only exclusively modified.
- The invariant: if node  $i$  becomes a child of node  $j$  in round  $t$ , then  $i$  and  $j$  have distance  $2^t$  in the original forest, provided  $j$  is not a root.
  - ▶ The base case: the claim is true for  $t = 0$ .
  - ▶ The inductive step: If  $i$  is a child of  $k$  in round  $t$  and becomes a child of  $j$  in round  $t + 1$ , then
    - ★  $i$  and  $k$  as well as  $k$  and  $j$  have distance  $2^t$  in  $F$ .
    - ★ hence  $i$  and  $j$  have distance  $2^{t+1}$  in  $F$ .

- Pointer jumping is a CREW-PRAM algorithm.
- If  $F$  is a forest with  $n$  nodes and depth  $d$ , then the root is determined for any node in time  $O(\log_2 d)$  with  $n$  processors.

# List Ranking

- A singly linked list of  $n$  nodes is represented by a shared array  $S$ .  $S[i]$  is the successor of  $i$ , resp.  $S[i] = 0$  if  $i$  has no successor.
- Each node  $i$  has a value  $V[i] = a_i$ .

Determine all suffix sums  $a_n, a_{n-1} * a_n, \dots, a_1 * a_2 * \dots * a_n$  for an associative operation  $*$ .

- Applications:

- ▶ If  $V[i] = 1$  for all  $i$ , then  $a_i * \dots * a_n$  is the distance (plus one) of the  $i$ th list element from the end of the list.
- ▶ For  $x * y = \max\{x, y\}$  the “sum”  $a_1 * \dots * a_n$  is the maximum of  $\{a_1, \dots, a_n\}$ .

- In comparison to the prefix problem:

- ▶ we now determine suffix sums instead of prefix sums.
- ▶ The **crucial** difference is the restricted access to list elements, instead of the random access for the prefix problem.

# List Ranking Via Pointer Jumping

```
for  $i = 1$  to  $n$  pardo
```

```
     $W[i] = V[i]; T[i] = S[i];$  // Save values and pointers.
```

```
    while ( $T[i] \neq 0$ ) do
```

```
        // We have not reached the end of the list.
```

```
             $W[i] = W[i] * W[T[i]];$  // Values are added.
```

```
             $T[i] = T[T[i]];$  // We perform pointer jumping.
```

- **Correctness:**

Before each iteration  $W(i)$  is the sum of all list elements, beginning in list element  $i$  and ending **before** list element  $T(i)$ .

- **Speed:**  $\Theta(\log_2 n)$  with  $n$  processors for a list of length  $n$ , provided the operation  $*$  can be evaluated in time  $O(1)$ .
- The algorithm can be implemented on a **EREW-PRAM**.

# Depth-first Search

- How to traverse a **graph** with a **parallel depth-first search**?
  - ▶ If we have to determine whether node  $u$  is visited before node  $v$  in a depth-first search started in node  $s$ , then there are in all likelihood no good parallel algorithms!
  - ▶ Parallelizations of depth-first search exist, but they are inefficient.
- We will see that **tree traversals** can be efficiently parallelized, namely computing the ordering of nodes according to a **preorder**, **postorder** or **level order** traversal.
- How does depth-first search work when applied to trees?
  - ▶ Starting at the root, **dfs** follows the tree edges to reach a leaf.
  - ▶ After reaching a leaf, the traversed edges are traversed again, but now in backwards direction.
  - ▶ Depth-first search stops, when all edges are traversed exactly once in either direction.

$T = (V, E)$  is an (undirected) tree.

- $\text{Euler}(T) := (V, \{(i, j) \mid \{i, j\} \in E\})$  is the “Euler graph” of  $T$ .
- An **Euler tour** is a path in  $\text{Euler}(T)$  which traverses all edges of  $\text{Euler}(T)$  exactly once and returns to its starting point.

- Euler tours of  $\text{Euler}(T)$  correspond to a depth-first search traversal of  $T$  and vice versa.
- How to compute Euler tours fast?
  - ▶ If  $T$  is given by its adjacency list representation, then the linked list  $N[v]$  collects all neighbors of a node  $v$ .
  - ▶ Each linked list orders neighbors according to their position within the list.
  - ▶ If we have already constructed a partial Euler tour with last edge  $(u, v)$ : with which edge should we continue?



# Constructing an Euler Tour Edge by Edge

- If  $(u, v)$  is the last edge of a partial Euler tour and
- if  $w$  is the right circular neighbor of  $u$  in the list  $N[v]$ , then continue the tour with the **successor edge**  $(v, w)$ .

We verify correctness by induction on the number of nodes.

- Let  $l$  be a leaf with parent  $v$ .  $N[v] = (\dots, u, l, w, \dots)$  is the list of  $v$ .
- Remove  $l$  and we obtain the tour  $T = (\dots, u, v, w, \dots)$ .
- What does the recipe require for the original graph?
  - ▶ after edge  $(u, v)$  continue with edge  $(v, l)$ .
  - ▶ The list  $N[l]$  consists only of  $v$ :  
since  $v$  is its own right circular neighbor, continue with edge  $(l, v)$ .
  - ▶  $w$  is the right neighbor of  $l$  in  $N[v]$ : the next edge is  $(v, w)$ .
- Thus we get the tour  $T = (\dots, u, v, l, v, w, \dots)$  in the original tree.

The recipe works.

# Input Representation

We assume that a tree is given as an **adjacency list with cross references**:

- the adjacency list  $N[v]$  of a node  $v$  is given as a circular list and
  - for any element  $w$  in  $N(v)$  there is a link to element  $v$  in  $N(w)$ .
- 
- What is the successor of edge  $(u, v)$ ?
    - ▶ Determine  $v$  in the list  $N[u]$ .
    - ▶ Follow the cross reference from  $v$  (in  $N[u]$ ) to get to  $u$  (in  $N[v]$ ).
    - ▶ Then determine the right neighbor  $w$  of  $u$  in  $N[v]$  and  $(v, w)$  is the successor of  $(u, v)$ .
  - The list of an Euler tour can be determined in constant time with  $2 \cdot |E| = 2(n - 1)$  processors.  
(The adjacency list contains  $2(n - 1)$  elements, since each edge occurs twice.)

# Traversing Trees in Parallel

Let  $T = (V, E)$  be an undirected **rooted tree** which is presented as an **adjacency list with cross references**. The following problems can be solved on an EREW-PRAM in time  $O(\log_2 |V|)$  with  $\frac{|V|}{\log_2 |V|}$  processors:

- 1 Determine the parent “parent( $v$ )” for each node  $v \in V$ .
- 2 Determine a postorder numbering.  
Postorder visits the children first and then the parent.
- 3 Determine a preorder numbering.  
Preorder visits the parent first and then the children.
- 4 Determine a level-order numbering: assign to each node its depth.
- 5 Determine the number of descendants for every node  $v \in V$ .

# The Euler Tour Algorithm

- (1) Determine an Euler tour beginning in the root.
- (2) Assign weights  $w(e)$  to edges  $e$  of Euler( $T$ ).  
// The weight assignment is problem dependent.
- (3) Apply list ranking, with addition as operation, to the **reversed** list of the Euler tour, i.e., compute prefix sums.
- (4) Evaluate the prefix sum  $\text{value}(e)$  for each edge  $e$ .

## Resources

If steps (2) and (4) run in time  $O(1)$ , then list ranking is the most expensive step.

# Determining Parents

- Assign the weight  $w(e) = 1$  for all edges.
- $\text{parent}[v] = u$  iff  $\text{value}(u, v) < \text{value}(v, u)$ . Why?

$u$  is the parent of  $v \iff$  The Euler tour visits  $u$  before  $v$   
 $\iff \text{value}(u, v) < \text{value}(v, u)$ .

# The Postorder Numbering

- First determine  $\text{parent}[u]$  for all nodes  $u$ .
- Then assign the weight  $w(u, \text{parent}(u)) = 1$ ,  $w(\text{parent}(u), u) = 0$ .
  - ▶ Only child→parent edges are counted.
  - ▶ If  $(\dots, u, \text{parent}[u], \dots)$  is the Euler tour, then  $\text{value}(u, \text{parent}(u))$  is the number of child→parent edges **before and including** edge  $u \rightarrow \text{parent}[u]$ .
  - ▶ Postorder visits a parent after all of its children  $\Rightarrow$   $u$  is visited right before the edge  $u \rightarrow \text{parent}[u]$  is traversed.
- $\text{post}(u) = \begin{cases} n & u \text{ is the root,} \\ \text{value}(u, \text{parent}(u)) & \text{otherwise} \end{cases}$  is a postorder numbering.

# Preorder Numbering

- First determine  $\text{parent}[u]$  for all nodes  $u$ .
- Then assign the weight  $w(u, \text{parent}(u)) = 0$ ,  $w(\text{parent}(u), u) = 1$ .
  - ▶ Only parent→child edges are counted.
  - ▶ If  $(\dots, \text{parent}[u], u \dots)$  is the Euler tour, then  $\text{value}(\text{parent}(u), u)$  is the number of parent→child edges **before and including** edge  $\text{parent}[u] \rightarrow u$ .
  - ▶ Preorder visits a parent before it visits its children  $\Rightarrow$   $u$  is visited right after the edge  $\text{parent}[u] \rightarrow u$  is traversed.
- $\text{pre}(u) = \begin{cases} 1 & u \text{ is the root,} \\ \text{value}(\text{parent}(u), u) + 1 & \text{otherwise} \end{cases}$  is a preorder numbering.

# Level-order Numbering

- First determine  $\text{parent}[u]$  for all nodes  $u$ .
- Then assign the weight  $w(\text{parent}(u), u) = 1$  to capture that depth increases by one and  $w(u, \text{parent}(u)) = -1$  to capture that we move back up to decrease depth by one.
  - ▶ If  $(\dots, \text{parent}[u], u \dots)$  is the Euler tour, then  $\text{value}(\text{parent}(u), u)$  is the depth of node  $u$ .
- Hence  $\text{level}(u) = \begin{cases} 0 & u \text{ is the root,} \\ \text{value}(\text{parent}(u), u) & \text{otherwise} \end{cases}$  is the level-order numbering.



# Counting the Number of Descendants

- First determine  $\text{parent}[u]$  for all nodes  $u$ .
- Set  $w(u, \text{parent}(u)) = 1$ ,  $w(\text{parent}(u), u) = 0$ .
  - ▶ Each node  $u$  is counted once by counting its “back edge”  $u \rightarrow \text{parent}[u]$ .
  - ▶  $\text{value}(u, \text{parent}[u]) - \text{value}(\text{parent}[u], u)$  counts all  $v \rightarrow \text{parent}[v]$  edges traversed after visiting  $u$  for the first time and before leaving  $u$  for the last time.
- Hence  $\text{size}(u) =$   
$$\begin{cases} n & u \text{ is the root,} \\ \text{value}(u, \text{parent}(u)) - \text{value}(\text{parent}(u), u) & \text{otherwise} \end{cases}$$
  
is the number of descendants of  $u$ .

# Arithmetic Expression Trees

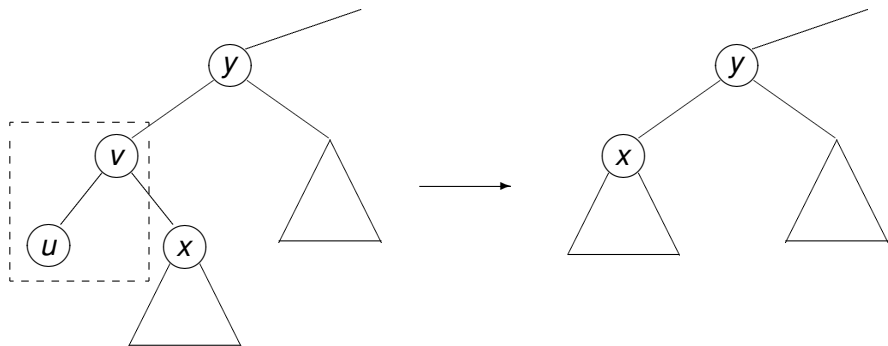
An expression tree  $T = (V, E)$  is a binary tree:

- its inner nodes have degree exactly two and they are labeled with either  $+$ ,  $-$ ,  $\cdot$  or  $/$ .
- Leaves are labeled by real numbers.

Evaluate the corresponding arithmetic expression.

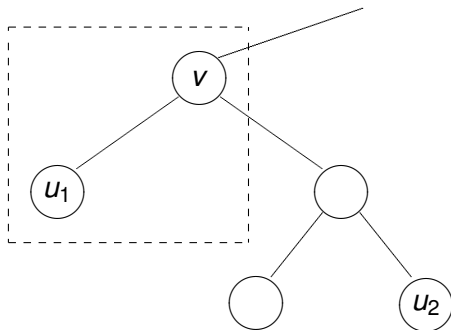
- We again assume that the tree is represented as an adjacency list with cross references.
- The approach: apply a sequence of **contraction steps**.
  - ▶ Each contraction removes one half of all leaves.
  - ▶ Combine evaluation with contraction
  - ▶ and we are done after logarithmically many contractions.

# Contractions



- A contraction step for  $u$ :
  - ▶ Remove leaf  $u$  and its parent  $v$ .
  - ▶ Make the sibling  $x$  of  $u$  a child of grandparent  $y$ .
  - ▶ The sibling  $x$  “remembers” the value of  $u$ .
- Neither sibling  $x$  nor grandparent  $y$  may be removed by other contractions.

# Collisions among Contractions



- We get collisions even if we only remove leaves in odd position.
  - ▶ if we remove leaf  $u_1$ , then  $v$  is removed as well.
  - ▶ if  $u_2$  is removed, then grandparent  $v$  has to survive.
- The way out:
  - ▶ First remove **left** leaves in an odd position and then **right** leaves in an odd position.  $u_1$  is removed first and afterwards  $u_2$ .
- How to determine leaves in odd position?

# Finding Leaves in Odd Position

- (1) Determine an Euler tour of Euler( $T$ ).
- (2) A node is a leaf iff it has exactly one neighbor.
- (3) Set  $w(e) = \begin{cases} 1 & e = (u, l) \text{ for a leaf } l, \\ 0 & \text{otherwise;} \end{cases}$
- (4) Determine the prefix sums  $\text{value}(\text{parent}[l], l)$  for all leaves  $l$  via list ranking.  
//  $\text{value}(\text{parent}[l], l)$  is the number of leaves to the left of  $l$ .
- (5)  $l$  is in odd position iff  $\text{value}(\text{parent}[l], l)$  is odd.

# The Contraction Process

- (1) Select all leaves in odd position.
- (2) while there are more than three leaves do
  - Apply a contraction step to all **left** leaves in odd position and
  - then apply a contraction step to all **right** leaves in odd position.  
// We still have to worry about evaluating removed nodes.

## The analysis:

- After one contraction step only leaves in even position remain.
  - ▶ The number of remaining leaves is halved.
  - ▶ There are  $O(\log_2 n)$  contraction steps.
- Leaves in odd positions have to be determined only once: just divide positions of the remaining leaves by two.
- The running time is bounded by  $O(\log_2 n)$ , if we use  $\frac{n}{\log_2 n}$  processors. (Euler tours are now computed in time  $O(\log_2 n)$ .)

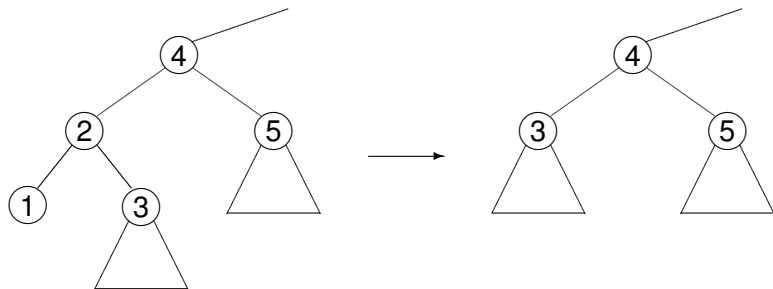
# Combining Contraction and Evaluation

- All nodes compute rational functions.
- Assume that the original subtree of  $v$  computes the value  $x_v$ .
  - ▶ Throughout we represent the value of a node  $v$  by the rational function

$$\frac{ax_v + b}{cx_v + d}$$

- ▶ Initially  $a = d = 1$  and  $b = c = 0$ .
- Contraction steps change coefficients.

# Combining Contraction and Evaluation: An Example



- We perform a contraction step removing leaf 1.
- The function  $\frac{ax_3+b}{cx_3+d}$  of node 3 has to be modified. Node 1 computes the value  $e$ .
  - ▶ if node 2 divides:  $\frac{e}{\frac{ax_3+b}{cx_3+d}} = \frac{(ec)x_3+(de)}{ax_3+b}$  is the new function.
  - ▶ if node 2 adds:  $e + \frac{ax_3+b}{cx_3+d} = \frac{(a+ec)x_3+(b+ed)}{cx_3+d}$  is the new function.